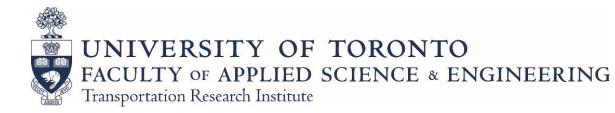
## ONE-ITS2.0: Automating Multi-Stakeholder ITS Cyber-Physical Service Integration in the Internet of Everything Context

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#### Outline

- Background and Motivation
- A Three-Pillar Framework to Support Seamless Coordination of Cyber-Physical ITS
  - -Integrated Service Execution (ISE)
  - -Integrated Service Planning (ISP)
  - –Ontological Semantic Knowledge Representation (OSKR)
- A Proof-of-Concept ATIS Prototype
- Conclusions



#### Research Objectives

# Intelligent Transportation System of Systems (ITSoS)

- To avoid the need to design, implement, and maintain large and complex regional **monolithic** systems.
  - Support greater connectivity and convergence of existing ITS sensors, services, and applications in the context of Internet of Things (IoT). (Semantic interoperability)
  - Facilitates collaboration and coordination across transportation stakeholders to design regional ITS plans. (Coordinated Planning)
  - Facilitates dynamic execution of ITS Plans to achieve stakeholders' common objectives. (Automatic Integration)



### Monolithic systems vs SoS





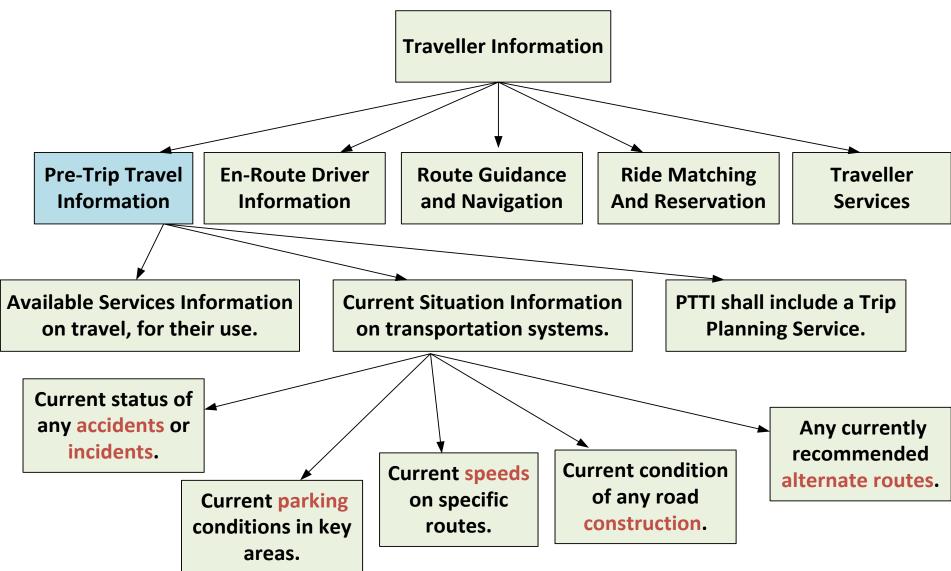


## Key SoS Characteristics (Maier, 1998)

- Operational Independence of the SoS elements
- Managerial Independence of the SoS elements
- Evolutionary Development
- Emergent Behavior
- Geographic Distribution

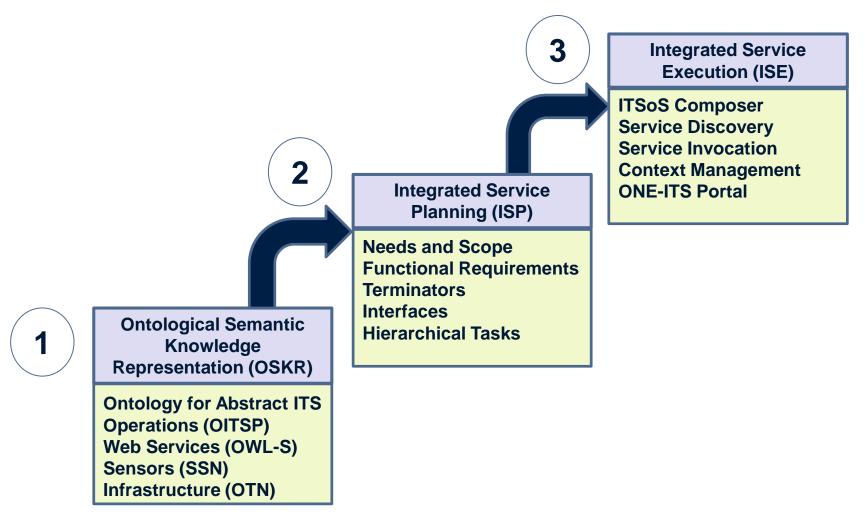


#### **Motivational Example**





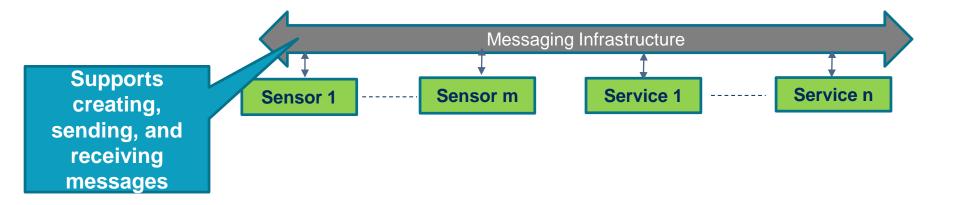
#### A Three-Pillar Framework to Support Seamless Coordination of Cyber-Physical ITS











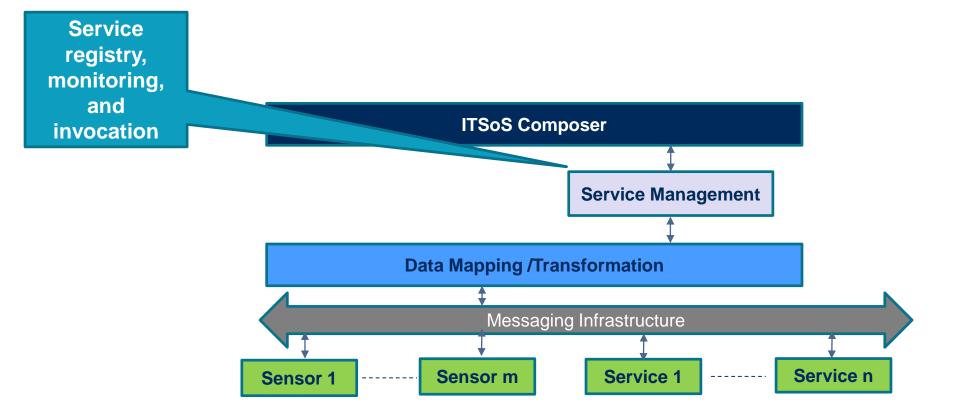


Service Orchestration (Discovery & Composition)

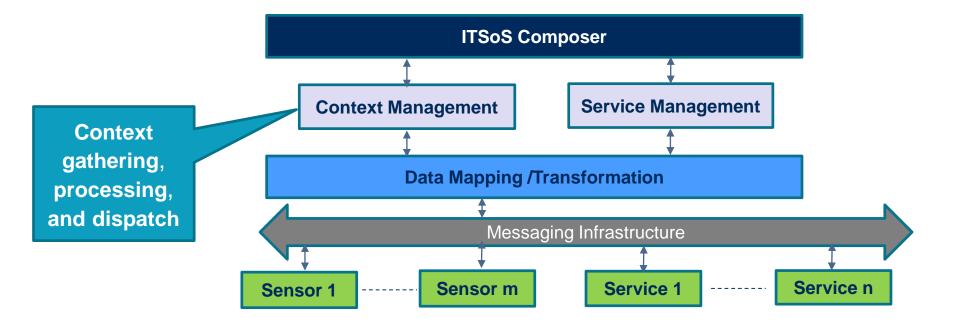
**ITSoS Composer** 



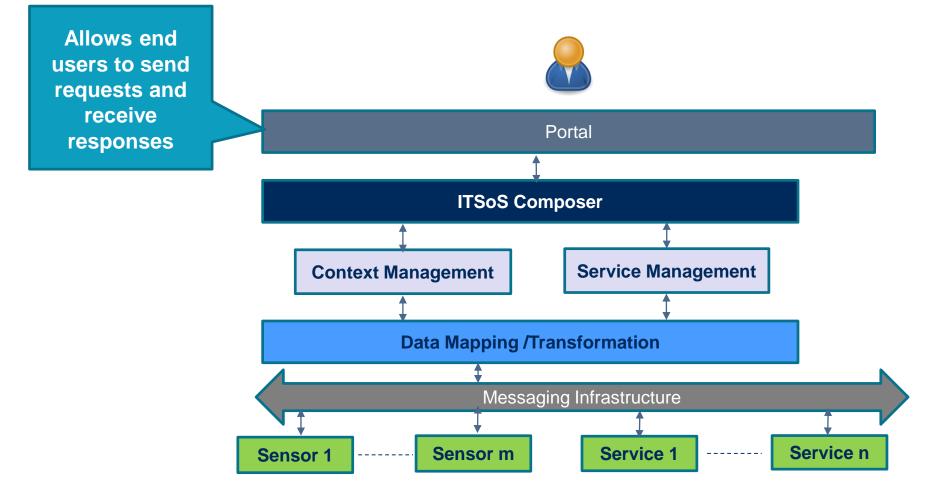






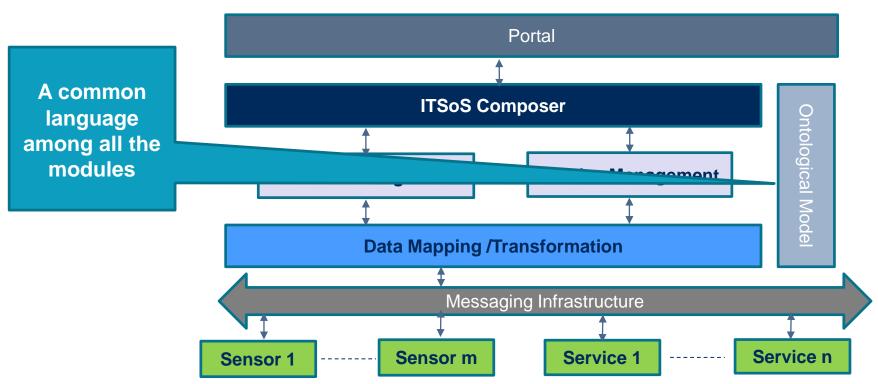














1) Identify Needs and Scope

2) Determine Key Services and Functional Requirements

3) Define Terminators and Interfaces

4) Develop an Operational Procedure (Task Network Definition)



Concerned Stakeholders Overall Goals Geographic Boundaries Timeframe 1) Identify Needs and Scope

2) Determine Key Services and Functional Requirements

3) Define Terminators and Interfaces

4) Develop an Operational Procedure (Task Network Definition)



1) Identify Needs and Scope

2) Determine Key Services and Functional Requirements

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4) Develop an Operational Procedure (Task Network Definition)

Select the standardised ITS User Services, Processes, Equipment Packages, and Functional Requirements



1) Identify Needs and Scope

2) Determine Key Services and Functional Requirements

3) Define Terminators and Interfaces

4) Develop an Operational Procedure (Task Network Definition)

Defines the terminators interacting with the application and the interfaces Equipment Packages, communicating the messages among the consistent components of the ITSoS application



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1) Identify Needs and Scope

2) Determine Key Services and Functional Requirements

3) Define Terminators and Interfaces

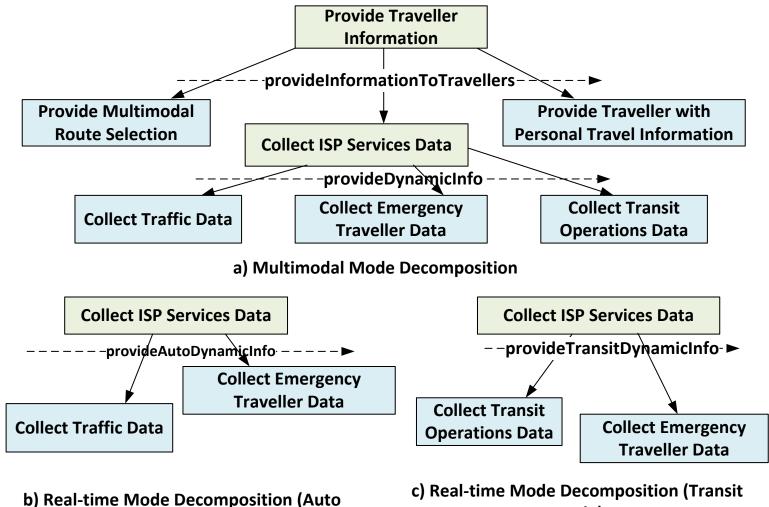
4) Develop an Operational Procedure (Task Network Definition)

Use the *Hierarchical Task Analysis (HTA)* to define tasks, subtasks, sequence of execution, and conditions for triggering the actions



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#### Example: Abstract ITS plan of an ATIS Operation

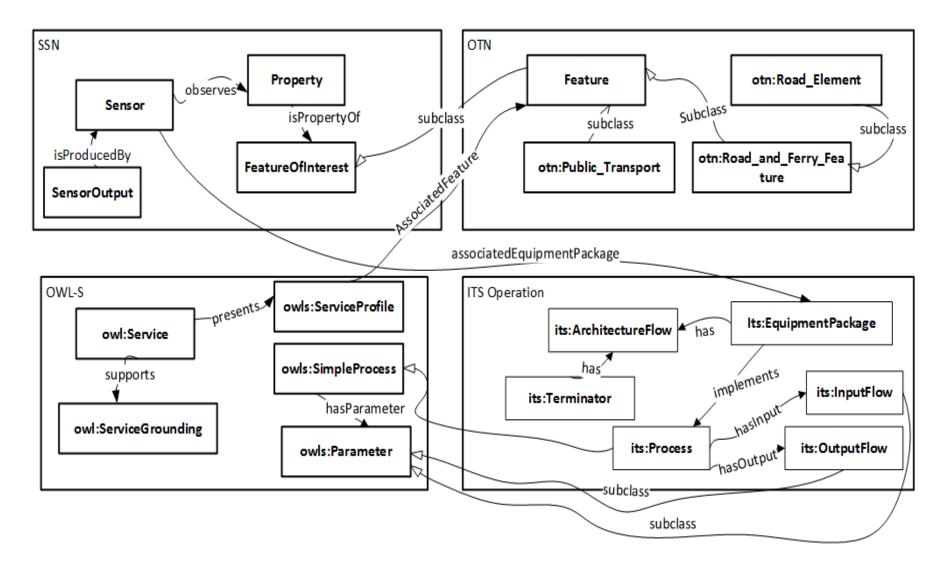


Mode)



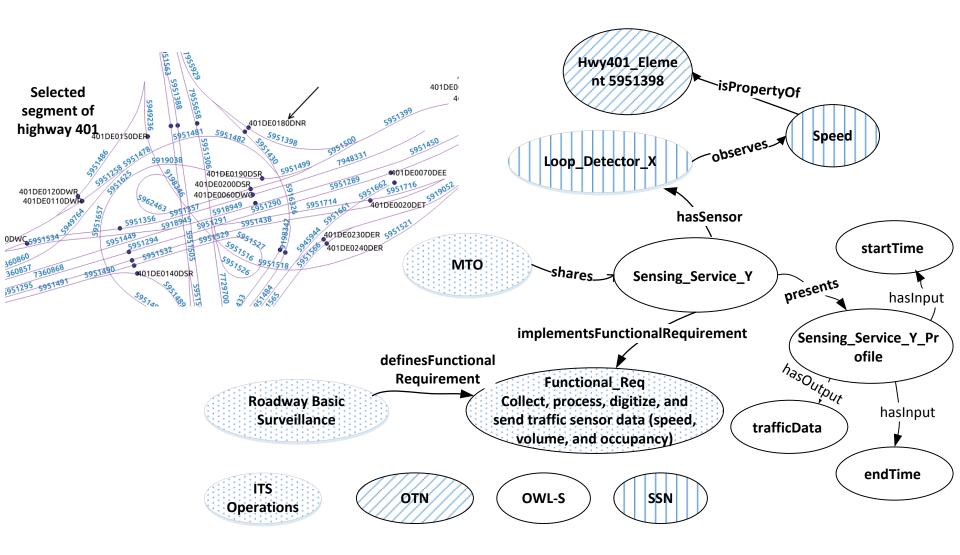
Mode)

#### **Ontological Semantic Knowledge Representation (OSKR)**



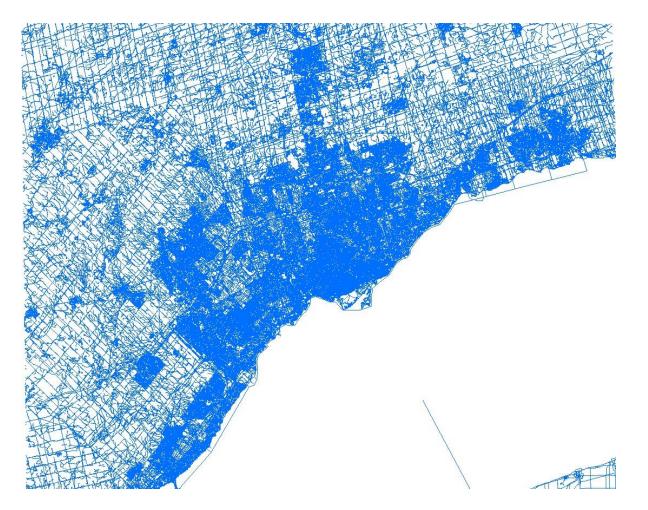


#### Example





#### **Open Street Maps**

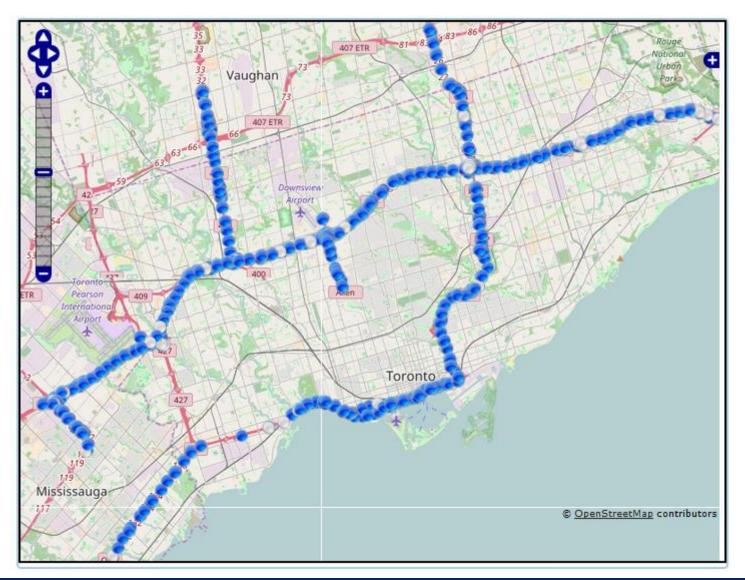


TTC GO YRT Brampton Transit Oakville Transit Durham Region Transit Burlington Transit MiWay

**GTFS** 



#### Sensors

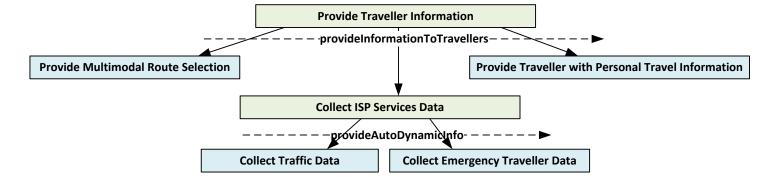




Service	ITS Abstract Process		
GTAPlannerService	Provide Multimodal Route		
	Selection		
IncidentListInqRq	Collect Emergency Traveller Data		
GTATrafficService	Collect Traffic Data		
NextBusMessagesService	Collect Transit Operations Data		
GTAStopsService	Collect Transit Operations Data		
NextBusPredictionsService	Collect Transit Operations Data		









401

Toronto

Origin =43.81967, -79.33022

401

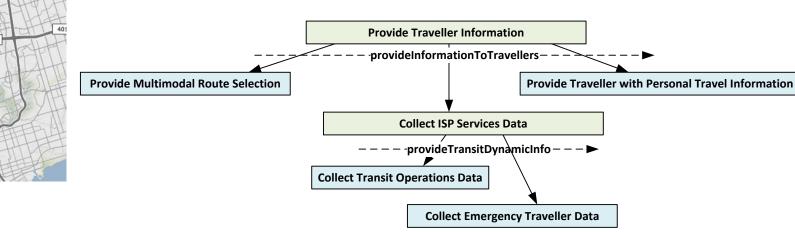
6:23

401

Toronto

Destination =43.65943, -79.38789 Modes = WALK, TRANSIT **Services:** 

NextBusMessagesService (for route 53, 1) GTAStopsService (for stops 10138, 14111) NextBusPredictionsService (for stops 10138, 14111)





Origin =43.80257, -79.39476 Destination =43.68674, -79.39991 Mode=CAR\_PARK,WALK, TRANSIT

6:15

401

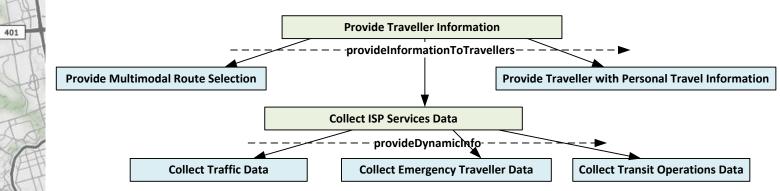
Tornto

#### Services:

GTATrafficService

IncidentListInqRq

NextBusMessagesService (for route 1) GTAStopsService (for stops 14111) NextBusPredictionsService (for stops 14111)



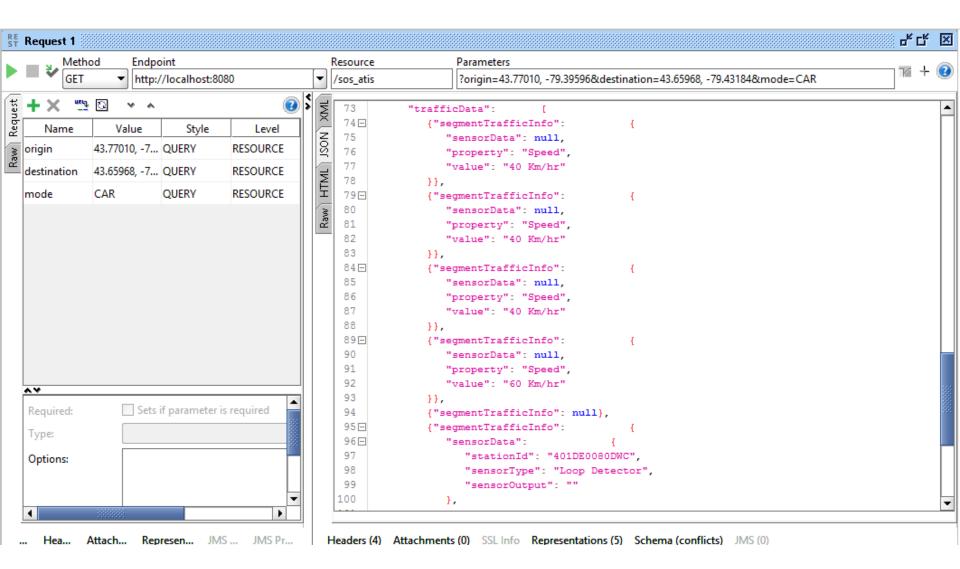


### An Example Request

	 ×
Method Endpoint Resource Parameters	
GET Vinteriod kesource Parameters GET Vinteriod kesource Parameters (sos_atis ) (rigin=43.77010, -79.39596&destination=43.65968, -79.43184&mode=CAR	 • 🕐
ta + X ™ 🖸 👻 ∧ 🔞 🔰 🔤 1⊡ {"routeSegment": [{	
News Velas Cola Land Land Z "routesegmentmode": "CAR",	
Vame     Value     Style     Level       origin     43.77010, -7     QUERY     RESOURCE     3 =     "routeSegmentData": {       ************************************	333
6 "routeSegmentEstimatedTravelTime": "1880",	
8       {         9       "distance": "44.85200000000004",         10       "streetName": "Elmwood Avenue",         11       "absoluteDirection": "WEST",         12       "relativeDirection": "DEPART",         13       "longitude": "-79.39599121336225",         14       "latitude": "43.77017845940073"         15       },         16       {         17       "distance": "572.2270000000001",         18       "streetName": "Wilfred Avenue",         19       "absoluteDirection": "SOUTH",         20       "relativeDirection": "LEFT",	
▲▼ 21 "longitude": "-79.39652810000001",	
Required: Sets if parameter is required   Type:   Options:        22   "latitude":   "4     Sets if parameter is required     22   "latitude":   "4     Sets if parameter is required     22   "latitude":   "4     Sets if parameter is required   23   24   4     25   "distance":   ************************************	•

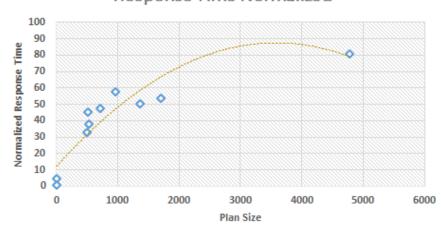


## An Example Request (Cont.)

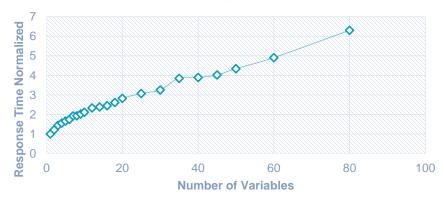




#### **Computational Performance Evaluation of the ITSoS Composer**



## Effect of Increasing the number of discovery variables



Initial Task	Plan Size	Normalized Response Time
Complete traveller information services	4770	80.64
Pre-trip travel information	1711	53.89
En-route driver information	495	32.72
Route guidance and navigation	959	57.43
Ride matching and reservation	709	47.52
Travel-related services and facilities	1370	50.58
Trip planning service	537	38.21
Provide information on current situational information on transportation systems	519	45.17
Collect Traffic Data	9	4.58
Collect Highway Traffic information	1	1

**Response Time Normalized** 

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#### Conclusions

The ITS standards provide a solution to the *syntactical* barriers of achieving interoperability within an ITSoS, however, they do not overcome the *semantic* interoperability barriers that hinder the ability of the ITSoS to dynamically compose its constituent components.



### Conclusions

- The ITS standards provide a solution to the *syntactical* barriers of achieving interoperability within an ITSoS, however, they do not overcome the *semantic* interoperability barriers that hinder the ability of the ITSoS to dynamically compose its constituent components.
- There is a *gap* between the *general* processes, as represented by the ITS architecture, and the *real* processes developed by the transportation jurisdictions and municipalities. Such gap precludes the ability to use the architecture in the planning of ITSoS applications.



#### Conclusions

- Enabling an ITSoS requires:
  - A common model that formally represent involved cyber-physical components. The thesis suggests a *four-tier ontology* that acts as a common language describing ITSoS operations.
  - A consistent method by which stakeholders can use the reference model to define and adjust abstract ITSoS plans. The thesis suggests a *hierarchical task analysis* approach to formally describe these abstract plans.
  - An *execution engine* to compose and coordinate the constituent cyber-physical components of the ITSoS. The thesis suggest an architecture illustrating the main component of the engine.





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